

ENTRAINING CURRENTS IN HOMOGENEOUS PLASMA

A Thesis

Presented to The  
School of Graduate Studies  
and  
The Faculty of Science  
Addis Ababa University

In Partial Fulfillment of the  
Requirements for the Degree  
Master of Science in Physics

by

Tesfaye Abraha

June, 1981

ADDIS ABABA UNIVERSITY

School of Graduate Studies

ENTRAINING CURRENTS IN HOMOGENEOUS PLASMA

by

Tesfaye Abraha

Faculty of Science

Approved by the Examining Board:

Dr. Jurgan Weissbarth

External Examiner

J. Weissbarth

Dr. V. Schepilov

Advisor

V. Schepilov

Dr. J. Netchaev

Member

J. Netchaev

Dr. S.C. Chhajlany

Chairman

S.C. Chhajlany

ACKNOWLEDGEMENT

I offer my gratitude to my Advisor and Instructor Dr. V. Schepilov for his guidance and supervision of this work.

I also thank the Acquisition Department of the Addis Ababa University Library for its kind collaboration in ordering articles, not available here, from abroad.

Last but not least, I would like to express my indebtedness to Ato Girme Dagne for his assistance in the technical preparation of the thesis.

## ABSTRACT

The generation of entraining currents in a homogeneous plasma by means of high frequency electromagnetic waves, with a slowly varying amplitude are considered. The treatment is based on the Villosov's kinetic equation, from which quasi-stationary additional terms to the distribution function with respect to amplitude are obtained. Using the second order additional term to the distribution function, the densities of the current, energy and energy flux produced by the longitudinal waves are evaluated. In this calculations only the non-resonant particles are taken into account. The condition under which resonant particles can be neglected is also investigated. Results are presented in terms of longitudinal dielectric permittivity and its derivative with respect to frequency. This work is done with a possible application in a steady-state tokamak reactors.

## C O N T E N T S

	<u>Page</u>
Introduction .....	1
Chapter 1.    Controlled Thermonuclear Fusion and Tokamaks .....	3
1.1    Thermonuclear Fusion .....	3
1.2    Tokamaks .....	7
Chapter 2.    Production of Steady-State Currents	12
2.1    Waves in a Plasma .....	12
2.2    Generation of Steady-State Currents	15
2.3    Methods Employed for the Generation of Steady-State Currents in Tokamaks	20
Chapter 3.    Plasma Kinetic Theory: The Boltzmann Distribution .....	26
3.1    The Distribution of Molecular Velocities .....	28
3.2    Mean Values of Molecular Properties	29
3.3    The Boltzmann Equation .....	31
3.3.1 The Collisionless Boltzmann Equation	31
3.3.2 The Collisional Integral .....	35
3.4    The Equilibrium Solution of the Boltzmann Equation .....	40
3.5    The Maxwellian Distribution .....	43

Chapter 4.	Generation of Entraining Currents	
	by a Slowly Varying Amplitude Wave.	46
4.1	Successive Approximation of the	
	Distribution Function .....	46
4.2	Evaluation of Current Density,	
	Energy Density and Energy Flux	
	Density .....	52
4.3	Evaluation of the Time During which	
	Resonant Particles can be Neglected	55
Conclusion	.....	61
References	.....	63

## INTRODUCTION

Plasma may be defined as a large collection of approximately equal number of positively and negatively charged particles. Plasma has a tendency to be electrically neutral on a macroscopic level. Ionized gases are found naturally throughout most of the universe except on the surface of the cold planets, such as the Earth. The study of the property of matter which is highly ionized and where its properties are dominated by the dynamic behavior of the free charges is usually referred as classical plasma. The particles behave classically and the ionization is due to high temperature and low density. Quantum plasma is used to study solids (metals, semiconductors) [1].

At present, one of the most important branches of plasma research is in the area of controlled thermonuclear reactions. The goal of this research is to generate energy by means of the same reactions that take place in the sun. The fundamental process is that the nuclear fusion of the heavy isotopes of hydrogen into helium, with the subsequent release of energy.

In order for the reaction to take place, the reactants must be heated to a very high temperature ( $\sim 10^8 \text{ K}$ ) and must be confined in some convenient device. Tokamaks are installations which are used for this purpose. In these devices, the plasma is heated by toroidal current which is produced inductively. The charged particles are confined by means of the magnetic field produced by the toroidal current and by externally applied magnetic field. The most commonly used method for driving plasma

current in these devices is to induce a toroidal electric field in the plasma by means of a time varying magnetic flux. But this method can not operate in a steady-state fashion; therefore alternative methods capable of driving plasma current continuously are desirable. Neutral beams [2], heavy charged particle beams [3,4] and various waves [5-8,20] have been proposed for maintaining steady-state plasma current by imparting to the electrons the momentum needed to compensate the resistive losses or by making the resistivity asymmetric. Hence, the attractiveness of tokamaks as a thermonuclear reactors would be considerably enhanced if it were possible to provide steady-state toroidal currents in place of the pulsed ohmic heating current.

The main objective of this thesis is, to investigate the generation of entraining currents by using high frequency electromagnetic waves with a slowly varying amplitude. The treatment is based on the Vlasov equation, which is the collisionless Boltzmann equation. The distribution function is determined by successive approximation and using the second order approximation, the densities of the current, energy and energy flux produced in the field of the longitudinal wave will be evaluated. In the evaluation, only the non resonance particles will be taken into account. The condition as when the role of the resonant particles can be neglected will also be investigated.

- 3 -

CHAPTER 1

CONTROLLED THERMONUCLEAR FUSION AND TOKAMAKS

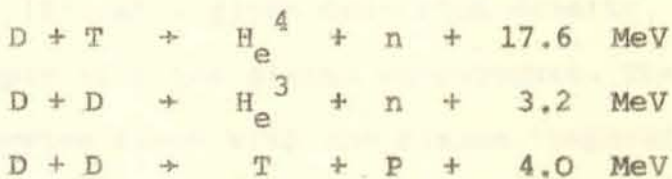
1.1 Thermonuclear Fusion:

The present revival of plasma physics is primarily due to the experimental attempts to produce controlled thermonuclear reactions. The continuous and rapid growth of industry throughout the world raises demands on energy which in the long run cannot be securely satisfied except in one way: by the reliable control of energy that is generated in the interior of the stars, and which in uncontrollable way is also released on Earth in the form of thermonuclear explosions.

Apart from being a virtually inexhaustible source of energy - considering that the reserves of deuterium in the oceans are estimated to suffice for many million of years - thermonuclear generation of energy has several additional advantages:

1. Safe operation of the thermonuclear reactor;  
Explosion can be virtually ruled out.
2. The extent of radioactive pollution is smaller than with fission type reactors.
3. With controlled thermonuclear reactions taking place in a plasma, thermal energy can be converted directly into electrical energy by magneto hydrodynamic |MHD| generators.

The elementary processes resulting in the release of thermonuclear energy on a macroscopic scale is the fusion (upon their collision) of two light nuclei of deuterium, tritium, etc. into the nucleus of a heavier element. Here are some of the most important reactions:



The symbols D, T stand here for the nuclei of deuterium and tritium (i.e., hydrogen isotopes of atomic weights 2 and 3) respectively,  $\text{H}_e^3$ ,  $\text{H}_e^4$  for nuclei of helium isotopes of atomic weights 3 and 4, and n and P are a neutron and a proton respectively. The number of MeV in each equation indicates the energy released by the fusion of a pair of nuclei.

The process of nuclear fusion, like any elementary process, is defined by its effective cross-section which indicates the probability of the process; on the other hand it defines the size of an impenetrable target area which one nucleus represents to another moving nucleus. After the impact of the moving nucleus onto this target, both nuclei fuse. In a plasma where the particles move at thermal velocities, the effective cross-section is a function of the relative velocity of the reacting particles or in equilibrium state, functions of the temperature.

Given the effective cross-section for the fusion of two nuclei, for a given density and plasma temperature, the frequency of occurrence per unit volume of this reaction can be computed. If we denote the number of reactions in D-T by  $z$ , the output released in  $1 \text{ cm}^3$  will be  $N = z \times 17.6 \text{ MeV} \times \text{se}^{-1}$  [9]. At a given deuterium density, this output rises steeply with the plasma temperature. The radiated output likewise rises with the plasma temperature, though somewhat more slowly. In the energy balance this later output figures as a loss. If the thermonuclear reactor is to supply useful power, the output generated by fusion of nuclei has to exceed this loss. Therefore, a specific temperature limit  $T_m$ , called ignition temperature exists for each total particle density  $n$ ; above this limit the reactor is capable of supplying energy [10, 24, 27].

The criteria required for pulsed fusion reactors has been derived by Lawson (1957) by considering the energy balance in a reacting plasma of density  $n$ , which was heated instantaneously to a temperature  $T$ , and held for some time  $\tau$ . The criteria is given by the following formula:

$$n \tau > 10^{14} \text{ cm}^{-3} \text{ sec}$$

Thus, in order to produce useful fusion power it is necessary to heat the plasma to a temperature of 10-20 KeV with a number density of  $10^{14}$ - $10^{15} \text{ cm}^{-3}$  and confinement time about one second [11].

Some of the fundamental demands on a thermonuclear reactor are the following:

- Of all the procedures aiming at the utilization of energy released in the fusion of light nuclei, the use of fully ionized high temperature plasma formed by such nuclei seems to hold the best promise.
- The thermonuclear reactor requires a device which permits the plasma to be heated above the ignition temperature of the reaction involved, that is to a temperature at which thermonuclear energy will be released at a rate at least capable of balancing the losses, mainly due to radiation.
- The particle density must be relatively small; otherwise the kinetic pressure  $p=nkT$  would exceed the technically sustainable value.
- As the energy loss due to Bremsstrahlung radiation increases with the square of the charge, the penetration into the plasma of the elements that have a higher atomic number must be prevented. Therefore, every thermonuclear reactor needs an ultrahigh vacuum pump which permits the thorough evacuation of the working space before it is filled with deuterium or tritium.
- Obviously no material used for the vessel containing the plasma can stand the enormous temperatures that are

required for controlled nuclear fusion. The plasma must therefore be insulated from the vessel in order to prevent it from being contaminated by materials evaporating from the walls. An approach suitable under terrestrial condition is the insulation by means of a magnetic field placed inside the vacuum.

- Using the MHD principle the energy released in the thermonuclear reactor can be converted into electric power. Heated by the thermonuclear energy released in the reaction, the plasma expands and cuts across the force lines of magnetic field confining it: an e.m.f. is thus developed in a suitably placed auxiliary windings.

The points listed above refer to the immediate requirements only. There are several additional problems, connected for instance with the expected copious flow of neutrons which cannot be confined in the magnetic vessel, since they carry no electric charge; there are problems regarding the stability of the reactor, etc. At present, research into thermonuclear reaction is mainly concerned with methods of heating and confining the plasma.

## 1.2, Tokomaks

Since the theme of the thesis is connected with the production of current in tokomaks, let us briefly discuss about these devices. A plasma with a temperature of several

million degrees has been sustained for some time in installations known as tokamaks, which are widely regarded as the most promising potential fusion reactors, with a high yield of temperature, number density and confinement time.

The name tokamak (derived from the Russian "toroidal - chamber - magnetic") is applied to axially symmetric toroidal systems in which the plasma is confined by a strong toroidal magnetic field  $B_t$ , produced by an external toroidal solenoid, together with a weaker poloidal field  $B_p$ , produced mainly by a toroidal current  $I_p$  flowing in the plasma itself. The main components of tokamak, together with the toroidal and poloidal magnetic fields are shown in Figures 1 and 2.

As shown in Figure 1, the main part of this device is the vacuum toroidal chamber, with coils to produce toroidal magnetic field  $B_t$ . The chamber is filled with hydrogen or its heavy isotopes at a pressure of  $10^{-4}$  -  $10^{-5}$  Torr. and serves as a secondary circuit of the transformer. Current is induced in the plasma by the action of the transformer. This current heats the plasma and produces poloidal magnetic field  $B_p$ .

The combination of the two fields, that is, the poloidal and toroidal magnetic fields produce nested toroidal

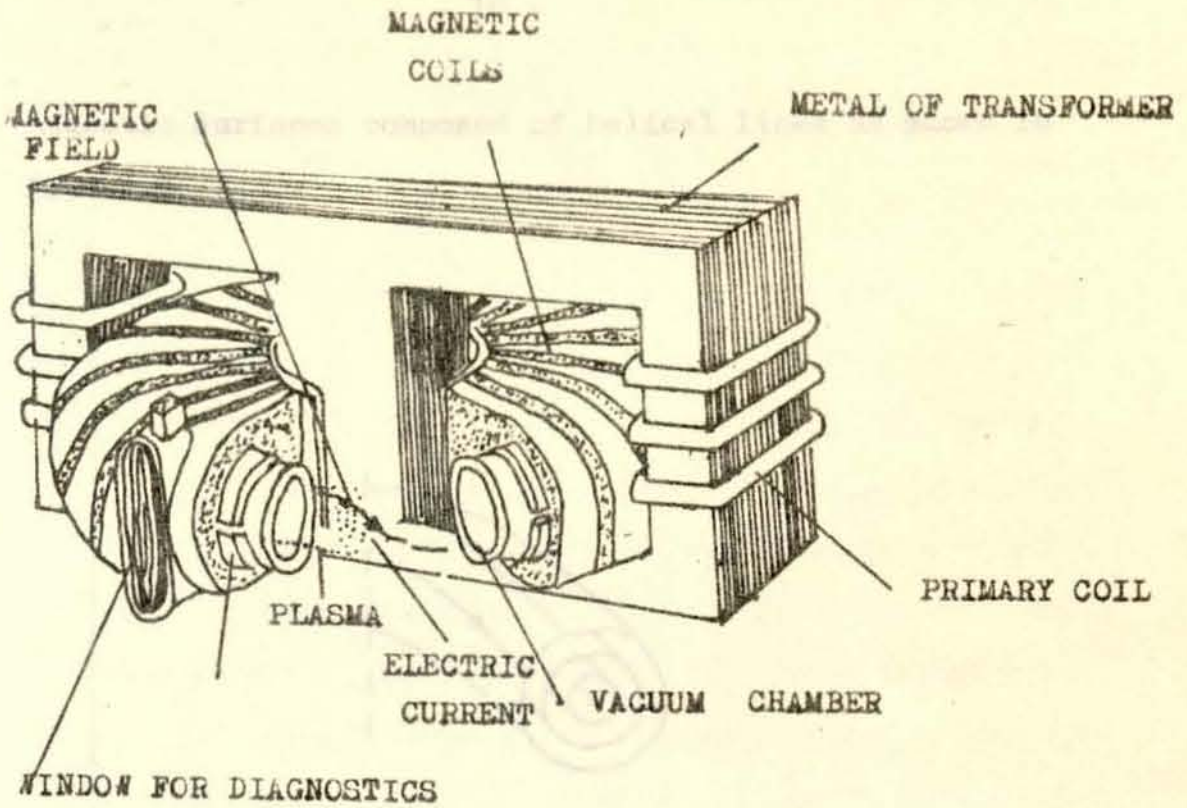


FIG. 1 THE MAIN PARAMETERS OF TOKAMAK

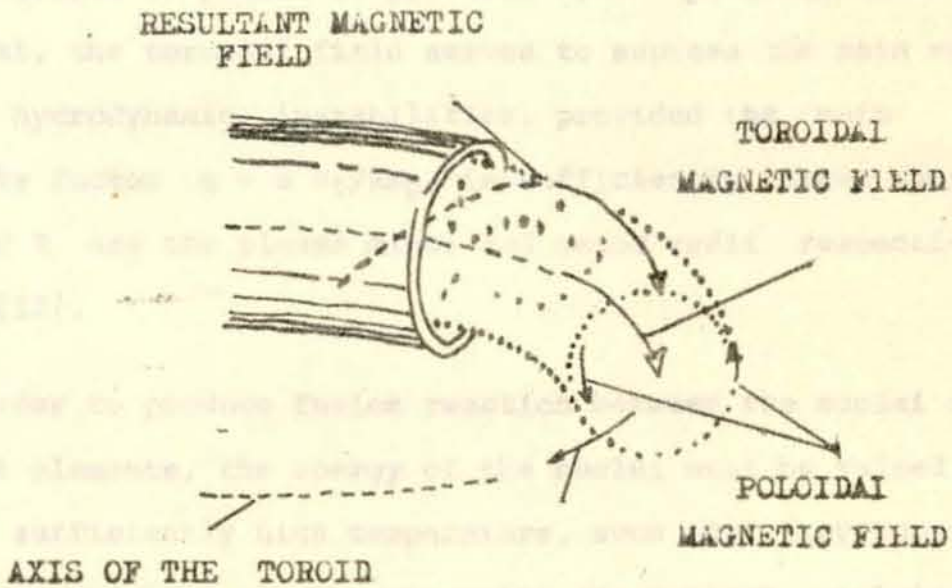


FIG. 2 THE TOROIDAL AND POLOIDAL MAGNETIC FIELDS

magnetic surfaces composed of helical lines as shown in Figure 3.

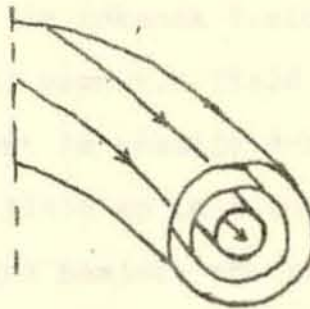


FIG. 3. TOROIDAL MAGNETIC SURFACES IN TOKAMAK.

Equilibrium of plasma is produced by the poloidal field whilst, the toroidal field serves to suppress the main magneto hydrodynamic instabilities, provided the main safety factor  $q = a B_t / R B_p$  is sufficiently large, where  $a$  and  $R$  are the plasma minor and major radii respectively|12|.

In order to produce fusion reaction between the nuclei of light elements, the energy of the nuclei must be raised to a sufficiently high temperature, such that they approach each other close enough overcoming the Coulomb repulsive barrier and it is necessary to confine the plasma for some

time. The toroidal current which is produced inductively is used to heat and confine the plasma.

Eventhough devices such as tokamak are considered as one of the most perspective ways of thermonuclear fusion they have some shortcomings. As has been pointed out earlier, plasma confinement in tokamak fusion devices is maintained in part by poloidal magnetic field sustained by a toroidal current. The current is usually driven by an inductively produced electric field so that the tokamak operates only in a pulsed mode and besides the magnetic field system is one of the most costly item in this device. Therefore, it was necessary to find an alternative method of producing toroidal currents which can be driven continuously so that, the tokamak will operate on a steady-state basis. Different methods of producing these currents have been suggested and will be considered in the next chapter.

electromagnetic waves, hyperacoustic waves and electrostatic waves. The analysis of these various types of waves is based primarily on Maxwell's equations

$$\nabla \times \mathbf{E} = -\dot{\mathbf{B}} \quad (2.1)$$

$$\nabla \cdot \mathbf{E} = \frac{\rho}{\epsilon_0} \quad (2.2)$$

$$\nabla \times \mathbf{H} = \mathbf{j} + \dot{\mathbf{D}} \quad (2.3)$$

$$\nabla \cdot \mathbf{H} = 0 \quad (2.4)$$

If we take the curl of equation (2.1) and differentiate equation (2.2) with respect to time, eliminating  $\mathbf{j} = \frac{1}{4\pi} \nabla \times \mathbf{H}$

## CHAPTER 2

### PRODUCTION OF STEADY STATE CURRENTS

A number of methods for achieving non-inductive current drive, all employing beams of radiation or particles have been suggested. For the generation of steady state currents with the help of waves, it was suggested to use different types of waves: lower-hybrid, Alfvén waves, ion cyclotron, electron cyclotron, electrostatic waves, etc. Before considering the various methods of producing steady-state currents in tokamak, let us briefly discuss the different types of waves and the basic principles for the production of current in a plasma.

#### 2.1 Waves in a Plasma

An ionized gas is capable of a wide variety of oscillatory motions. Considerable theoretical study has been given to three particular types of waves in a plasma: electromagnetic waves, hydromagnetic waves and electrostatic waves. The analysis of these various types of waves is based primarily on Maxwell's equations:

$$\vec{\nabla} \cdot \vec{E} = \rho / \epsilon \quad (2.1)$$

$$\vec{\nabla} \cdot \vec{B} = 0 \quad (2.2)$$

$$\vec{\nabla} \times \vec{E} = - \frac{\partial \vec{B}}{\partial t} \quad (2.3)$$

$$\vec{\nabla} \times \vec{H} = \vec{j} + \frac{\partial \vec{D}}{\partial t} \quad (2.4)$$

If we take the curl of equation (2.3) and differentiate equation (2.4) with respect to time, eliminating  $\vec{\nabla} \times \frac{\partial \vec{H}}{\partial t}$ ,

we obtain the basic equation for electromagnetic waves,

$$\nabla^2 \vec{E} - \vec{\nabla} \rho / \epsilon = \mu \frac{\partial \vec{j}}{\partial t} + \epsilon \mu \frac{\partial^2 \vec{E}}{\partial t^2} \quad (2.5)$$

In general, under any given set of circumstances four modes of infinitesimal wave propagation are possible at each frequency, although the phase velocity of some modes may be imaginary. The simplest situation is obtained when there is no external magnetic field. The modes are then of two types, electromagnetic and electrostatic. In electromagnetic waves, the electric field is perpendicular to the direction of propagation. There are two such modes, corresponding to the two directions of polarization. If the frequency is less than a certain critical value, which is called the plasma frequency, which increases with increasing density, the phase velocity becomes imaginary and electromagnetic waves cannot propagate in the absence of magnetic field.

The other two modes in the absence of a magnetic field are electrostatic type, in which the current density  $\vec{j}$  and the electric field  $\vec{E}$  are parallel to the direction of propagation. In one of these modes the positive ions are essentially unaffected and only the electrons oscillate. These oscillations are called electron or plasma waves. In the other mode, called positive ion waves, the positive ions and electrons, generally move together; the inertia of the ions determines the wave velocity, which is normally less than that of the electron waves. In the absence of a magnetic

field, the phase velocity of the electron waves becomes imaginary for frequencies less than the plasma frequency, while the positive ion waves don't propagate above a cut-off frequency equal to  $(m_e/m_i)^{1/2}$  times the plasma frequency [13].

In the presence of a magnetic field, these four modes are profoundly modified, but the number of independent modes remains the same. The term hydromagnetic wave is frequently given to the waves which arise in the presence of a magnetic field at a frequency small compared to the cyclotron frequency of the positive ions. An Alfvén wave is a simple type of hydromagnetic waves [13].

In analysing a dispersion relation, it is frequently helpful to examine the frequencies at which the velocity of the wave is either zero or infinity. The former are called resonances, since these are the frequencies at which a plasma will be in resonance with an applied oscillating transverse electric field. The latter are called cut-offs. At a cut-off, a wave is usually reflected, while at resonance either absorption or reflection may occur depending on the nature of the damping process involved.

When a wave propagates across a magnetic field, the extraordinary mode, which is partially transverse and partially longitudinal, will have two resonance frequencies at the lower-hybrid and the upper-hybrid, which are defined by:

$$\begin{aligned}\omega_{h1}^2 &= \omega_{ce} \omega_{ci} \\ \omega_{h2}^2 &= \omega_p^2 + \omega_{ce}^2\end{aligned} \quad |13|$$

where:  $\omega_{h1}$  is the lower-hybrid frequency

$\omega_{h2}$  is the upper-hybrid frequency

$\omega_p$  is the plasma frequency

$\omega_{ci}$  is the ion cyclotron frequency

and

$\omega_{ce}$  is the electron cyclotron frequency

At the upper-hybrid frequency, only the electrons oscillate and the resonant oscillations represent the joint influence of the electrostatic and magnetic forces on gyrating electrons perpendicular to both the magnetic field and the wave front. At the lower-hybrid frequency, electrons and ions oscillate together.

## 2.2 Generation of Steady-State Currents

Plasma currents driven by traveling waves were first observed by Thonemann, Cowhig and Daveport in 1952 [8,14]. In principle any wave with a net momentum can generate a current via any damping mechanism, caused by the charged particles in the plasma. The process of producing current is based on the transition of momentum of the wave to the electrons and ions in a plasma. This mechanism can be explained using the single particle cold plasma model. In this model only the motion of the electrons in the field of the high frequency electromagnetic wave is considered.

The equation of motion for the electrons is given by:

$$m \frac{d\vec{v}}{dt} = m \frac{d^2\vec{r}}{dt^2} = e \vec{E} \quad (2.6)$$

Taking the electric field of the plane mono-chromatic wave as:

$$\vec{E}(\vec{r}, t) = \vec{E}_0 \cos(\omega t - \vec{k} \cdot \vec{r}) \quad (2.7)$$

and neglecting the variations of this field on the amplitude of the electron oscillations, by substituting equation (2.7) into equation (2.6) we get:

$$m \ddot{\vec{r}} = e \vec{E}_0 \cos(\omega t - \vec{k} \cdot \vec{r}) \quad (2.8)$$

solving for  $\dot{\vec{r}}$  :

$$\dot{\vec{r}} = \frac{e \vec{E}_0 \sin(\omega t - \vec{k} \cdot \vec{r})}{m\omega} \quad (2.9)$$

From equations (2.8) and (2.9) the work done per unit time by the wave is obtained as

$$e \dot{\vec{r}} \cdot \vec{E} = \frac{e^2}{m\omega} |E_0|^2 \frac{1}{2} \sin 2(\omega t - \vec{k} \cdot \vec{r}) \quad (2.10)$$

From equation (2.10) , it follows that the average work done by the wave is equal to zero. Therefore, there is no regular interchange of energy between the wave and the electrons. In order to change the average energy of the electrons, it is necessary to have a phase difference between the velocity of the electrons and the field different from  $\pi/2$  . This can be achieved by using different methods.

a) Scattering by free charges,

If an electromagnetic wave falls on a system of charges, then under its action the charges are set in motion. This motion in turn produces radiation in all directions; there occurs, we say, a scattering of the original wave. The scattering is most conveniently characterized by the ratio of the amount of energy emitted by the scattering system in a given direction per unit time, to the energy flux density of the incident radiation. This ratio clearly has dimensions of area, and is called the effective scattering cross-section. [15,26].

The occurrence of scattering leads, in particular, to the appearance of a certain force acting on the scattering particle. One can verify this by the following considerations. On the average, in unit time, the wave incident on the particle loses energy  $\langle \omega \rangle \sigma$ , where  $\langle \omega \rangle$  is the average energy density, and  $\sigma$  is the total effective scattering cross-section. Since the momentum of the field is equal to its energy divided by the velocity of light, the incident wave loses momentum equal in magnitude to  $\langle \omega \rangle \sigma$ . The momentum lost by the incident wave is absorbed by the scattering particle. The average force acting on the particle is equal to the average momentum absorbed per unit time, i.e.,

$$\langle \vec{f} \rangle = \sigma \langle \omega \rangle \vec{n} \quad (2.11)$$

where  $\vec{n}$  is a unit vector in the direction of propagation of the incident wave.

The scattering cross-section is given by |16|

$$\sigma = \frac{8\pi}{3} \left( \frac{e^2}{mc^2} \right)^2$$

b) Collision of Particles:

When electrons collide with the neutral atoms or ions an average force acts on the electrons which is given by |17|

$$\langle \vec{f} \rangle = \frac{e^2 (\vec{k} \cdot \vec{E}) v \vec{E}_0}{2\omega m (\omega^2 + \nu^2)} \quad (2.12)$$

where  $\nu$  is the collisional frequency. From equation (2.12), it is seen that the average force is different from zero for longitudinal waves and is directed along the propagation of the wave. Steady-state current is produced if the average force acting on the electrons as given by equation (2.12) is equal to the force of friction which is given by  $M\nu\vec{v}$ . And when  $\nu < \omega$  current does not depend upon the frequency of collision.

c) Interaction of incident wave with resonant particles:

When the velocity of the electrons is close to the phase velocity of the wave, it is necessary to take into account the dependence of the electric field upon the coordinates in integrating the equation of motion of the electrons that is, equation (2.6). In this case, regular interchange of energy between the electrons and the wave takes place and the current produced by the electrons

can be evaluated using the kinetic theory of plasma. The generation of current is connected with the actions of a practically constant electric field which acts on the resonant electrons.

The resonant coupling between the wave and these electrons which are moving with approximately the same velocity as the phase velocity of the wave is known as Landau damping [18]. Particles moving slightly faster than the wave will decrease their average velocity to the phase velocity of the wave through resonant interaction and transfer their extra kinetic energy to the wave. Particles moving slightly slower than the wave will be accelerated and absorb energy from the wave. If the distribution function decreases with increasing velocity damping takes place, since there will be more slow particles to absorb energy from the wave than fast particles to transfer energy to the wave.

d) Non Homogeneous and Non Stationary Waves:

If the wave changes its amplitude, then, there will be a phase difference between the field and the velocity of the oscillatory particles which is propagational either to the gradient of the amplitude  $\frac{\partial A}{\partial r}$  or to the time change of amplitude  $\frac{\partial A}{\partial t}$ .

### 3 Methods Employed for the Generation of Steady-State Currents in Tokamaks

In this section the various methods proposed for the production of continuous toroidal currents in tokamak will be considered. These methods use either waves or beams of particles to produce steady-state currents. For the case of waves, the main idea is, net toroidal momentum is delivered to one of the species of the plasma, usually the electrons, from an external source. The momentum absorption by a particle leads to the production of current. In the other case, many systems for the production of high, energy intense directed beams of plasma electron, ions or neutral atoms are used. These beams are injected into a specially prepared region of plasma confinement where ionization of the neutral particles present can occur.

Fisch [5] has considered the production of continuous toroidal currents by means of radio frequency (rf) waves. These waves which can be injected continuously, have a net toroidal component of momentum, so that when absorbed by electrons, a force is exerted that drives a toroidal current. For practical employment in a reactor, the power required to drive the current must be a small fraction of the fusion out put. Since all types of waves do not incur the same power dissipation, in searching for the most favourable wave, we must consider not only the ease with which the waves can be excited, but also their individual power requirements. There are two types of waves that are

attractive in terms of minimizing the power dissipated for a given current generated, namely low and high parallel phase velocity waves. The former region of subthermal phase velocity was suggested by Wort [5] and it is attractive, because in this region waves have a higher momentum content per unit energy. In other words, whereas the momentum in a wave is proportional to its wave number  $k$ , the energy carried by the wave is proportional to its frequency  $\omega$ , so that waves with low  $\omega/k_z$  have a high parallel momentum content. ( $k_z$  is the wave number in the toroidal direction). When the energy of the wave is absorbed by the electrons, the momentum absorbed is proportionally higher. Wort envisioned the use of subthermal phase velocity, low compression Alfvén waves to achieve current generation.

The alternative approach of using waves with high phase velocities was pointed out by Fisch [18]. Although, these waves have little momentum content, their momentum and energy are absorbed by fast electrons. The electrons that carry the current are relatively collisionless and so retain their momentum longer than the thermal electrons, which carry the current when low phase velocity waves are employed. The relative infrequency of collisions encountered by the current carriers compensate for the dearth of momentum in the driving waves. This approach was originally envisaged employing the lower-hybrid wave with phase velocity parallel to the magnetic field several times the electron thermal velocity. Successful attempts of the production

of current by using lower-hybrid waves were reported by Jobs, F, etal [19].

The production of current by ion cyclotron waves was considered by Tajima [6]. In this method the plasma is irradiated by electromagnetic field in the ion cyclotron range of frequencies. Some of the attractive features of the ion cyclotron heating are:

- the low frequency of this scheme means that high power technology is available for wave generation,
- it would heat the plasma ions directly by either heating the bulk distribution or producing energetic tails which are more active,
- ion cyclotron heating might be an alternative to the expensive neutral beam heating, in terms of good penetration to the centre of the plasma.

In the works of Karney and Fisch [7] the generation of current by means of electron cyclotron wave absorption was considered. These waves are employed to generate toroidal current merely by heating selected electrons, and interestingly without directly injecting substantial toroidal momentum to those electrons. The effect of cyclotron heating is to increase primarily the perpendicular component of the velocity of the resonant electrons. The velocity increase lies in this direction because the waves have very little parallel momentum content compared to the energy content, so that when the wave is absorbed by the

electrons, the electron energy increases, but by momentum conservation, its parallel momentum barely increases. That the waves themselves have little momentum content to impart to the electrons is a consequence of the super-luminescent parallel velocity. The energy in a wave is proportional to the frequency while its momentum is proportional to the wave number  $k$ , and since  $\omega/k \gg c$  the wave possesses little momentum.

Toroidal currents produced by means of electrostatic waves was considered by Kenemitsu Kato [8]. In this work the general formula which gives the current density generated by an electrostatic traveling wave was derived in the framework of quasi-linear theory. For the case of high frequency electrostatic waves, in which the ion motion can be neglected, it was shown that no net plasma current is produced by the wave particle interaction. Here, the wave momentum is defined as the momentum of the non resonant electrons. When the wave is attenuated or growing, momentum is exchanged between the wave and the resonant electrons. If the momentum of the electron distribution function, which is the sum of the wave momentum and the momentum of the resonant electrons is initially zero, it must still vanish after the wave has damped out. Not only the resonant electrons but also the nonresonant electrons contribute to the current so that the currents generated by them cancel each other. And next, by considering low frequency

electrostatic waves, in which the motions of the ions are taken into account, it is shown that plasma current is generated not by momentum exchange between the electrons themselves but due to the momentum exchange between the electrons and the ions. But for the case of electromagnetic wave, which has field momenta as well as particle momenta, as the wave decays, the field momenta is converted to particle momenta therefore, even if the ions are considered to be immobile, the electrons gain momenta so that a plasma current is generated.

Manheimer and Winsor [3] considered the possibility of injecting intense pulsed ion beams into tokamak plasma in order to heat the plasma and maintain the current. In order to accomplish these objectives, several obstacles must be overcome. First, the ion beams must be produced; second it must be injected into the toroidal chamber, third it must deposit its energy in the plasma. The ion beam is injected into a partially formed plasma and is trapped and the remaining plasma is formed around it. Once the beam is trapped in the torus, the next question is coupling it to the plasma. By properly choosing the beam and plasma parameters, the energy of the beam can be absorbed by the plasma in a confinement time or less.

The production of steady-state current by high energy  $\alpha$ -particles produced by fusion reactor was considered by Bharda and Chu [4]. The idea is to use r f power to prohibit the  $\alpha$ -particles from slowing down isotropically and to

push the  $\alpha$ -particles in a preferential direction and thus form an  $\alpha$ -particle beam. The  $\alpha$ -particle beam will then transfer momentum to the electrons and thus sustain plasma current.

A basically different approach was proposed by Fisch and Boozer [21] in which no net toroidal momentum is injected, but the collisionality of plasma is somehow altered so that, for example electrons moving to the left collide more frequently with ions, than do electrons moving to the right. There would result a net current with ions moving to the left and electrons moving, on the average to the right. The means suggested for achieving this asymmetric resistivity is selective heating of those electrons moving to the right. The electrons being hotter naturally collide less.

In this thesis, the mechanism of generating entraining currents by using high frequency electromagnetic waves with a slowly varying amplitudes is considered which is a basically different approach from the above mentioned works. The current density, energy density and energy flux density which are produced by the passage of such waves will be evaluated using Vlasov's kinetic equation which is considered in the next chapter.

CHAPTER 3

PLASMA KINETIC THEORY: THE BOLTZMANN EQUATION

Kinetic theory attempts to explain the macroscopically observed phenomena of gases by considering the forces of interaction between the molecules of the gases. Free atoms, ions and electrons are considered merely as special types of molecules [22]. If at some instant of time, the position of each molecule of the gas and the forces that acted on each molecule, are known, the subsequent motion of the molecules can be determined in principle by classical mechanics. But it is not possible to get detailed information of the molecules and even if there is, the problem will be too difficult and time consuming to solve.

An alternative approach to the problem is through the methods of statistical mechanics. If we consider a box of gas containing  $n$  molecules at some instant of time, the three components of momentum and the three components of position of each molecule are given by a list of  $6n$  numbers. The entire gas at that instant of time is represented by a single point in the  $6n$  dimensional phase space. If we consider again a box of gas which may be the same box as considered previously, but at some later instant of time, it can be represented by another point in phase space. If the process is continued until all possible states are considered, the total number of points in phase space will be the different number of dynamical states of the particular system. These points are said to form an ensemble of points in phase space.

Statistical mechanics deals with the probability of finding one system of the ensemble, chosen at random, in a particular region of phase space. The assumption of statistical mechanics is that, the macroscopically observed variables of the gas correspond to those dynamical states that are most probable. The fundamental theorem of statistical mechanics is Liouville's theorem which states that, the volume occupied by a given set of points in phase space is constant through out the motion of these points. The solution of Liouville's equation gives the probability of finding a point at a given place in phase space. That is, we would know the probability that each molecule has a specified position and momentum. However, it is often unnecessary to have such a complete description of the gas and it would be sufficient to know only the probability that any single molecule has a given position and momentum. This part of statistical mechanics dealing with one particle distribution forms the framework of kinetic theory. For this case it is necessary to consider only a six dimensional phase space.

The distribution function of molecular velocities is defined as the density of points in phase space. This is a one particle distribution function, because the position and velocity of any given particle is not correlated with the position and velocity of any other particle or particles. If the distribution function of the molecular velocities is known, then the various molecular properties involving the pressure and energy of the gas can be obtained by integrating the quantity of interest times the distribution function over all velocity space.

### 3.1 The Distribution of Molecular Velocities

Consider a certain volume of gas, where the location of each molecule is represented by its position in a cartesian coordinate system. The differential volume element  $dr (= dx_1 dx_2 dx_3)$  is a small, but finite, volume element which is assumed to be large enough to contain a great number of molecules but which is, nevertheless, small compared to the lengths involved in spatial variation of the macroscopic parameters of the gas.

If  $N(x_1, t)$  is the number density of molecules in configuration space, then the number of molecules in  $dr$  is  $Ndr$ . A molecule is said to be in  $dr$  if the molecule is located at a position with its  $x_1$  - component between  $x_1$  and  $x_1 + dx_1$ , its  $x_2$  - component between  $x_2$  and  $x_2 + dx_2$ , and its  $x_3$  - component between  $x_3$  and  $x_3 + dx_3$ . All the molecules in  $dr$  have the same value of  $x_1$  as far as macroscopic variation of the gas are concerned.

The  $ndr$  molecules in  $dr$  have a wide range of different velocities. The velocities of the  $ndr$  molecules can be represented in a three dimensional velocity space. The density of the  $ndr$  points in velocity space is given by

$f(v_1, x_1, t)dr$ , where  $f$  is called the velocity distribution function. If  $dc (= dv_1 dv_2 dv_3)$  is a differential volume element in velocity space, then  $f dr dc$  is the number of points in the volume element  $dc$ . A molecule is said to be in  $dc$  if it has a velocity with components between  $v_1$  and  $v_1 + dv_1$ ,  $v_2$  and  $v_2 + dv_2$ , and  $v_3$  and  $v_3 + dv_3$ .

Now if  $f dr dc$  is the number of molecules in  $dr$  whose velocities are in  $dc$ , we see that  $f$  is the density of points in the six dimensional phase space made up of the three components of position and three components of velocity. Dividing  $f dr dc$  by the volume  $dr$  we note that  $f dc$  is the number of molecules per unit volume with velocity  $v_i$  in  $dc$ . If we integrate the expression  $f dr dc$  over all velocity space, we will obtain the total number of points in the six dimensional phase space. Thus,

$$\begin{aligned} ndr &= dr \int f dc \\ \text{and } N &= \int f dc \end{aligned} \tag{3.1}$$

## 2 Mean Values of Molecular Properties

Let us associate some molecular property  $\phi(v_i, x_i, t)$  with each of the  $ndr$  molecules in  $dr$ , which is in general a function of velocity  $v_i$ , position  $x_i$  and time  $t$ . At some time  $t$ , the values of  $\phi$  for the  $ndr$  molecules in  $dr$  will depend only on their velocity  $v_i$ , because the  $x_i$  dependence of  $\phi$  will be the same for all molecules in  $dr$ .

If we add up the values of  $\phi$  for the  $ndr$  molecules in  $dr$ ,

$$\phi(1) + \phi(2) + \dots + \phi(ndr) = \Sigma \phi$$

The mean value  $\langle \phi \rangle$  of  $\phi$  for the  $ndr$  molecules in  $dr$  is defined by the equation

$$\Sigma \phi = \langle \phi \rangle ndr$$

Some of the  $ndr$  values of  $\phi$  making up  $\Sigma\phi$  will have essentially the same value: namely, those whose velocities lie in the same velocity element  $dc$ . The number of such molecules is  $f dr dc$  and each contributes the quantity  $\phi$  to the sum  $\Sigma\phi$ . Thus, the contribution of all molecules with all velocities is found by integrating over all the velocities. Thus,

$$\Sigma \phi = \int \phi f dc \quad (3.2)$$

$$N \langle \phi \rangle = \int \phi f dc$$

From equations (3.1) and (3.2) we see that the mean value of any function  $\phi$  is found from

$$\langle \phi \rangle = \frac{\int \phi f dc}{N} = \frac{\int \phi f dc}{\int f dc} \quad (3.3)$$

Applying the above method we will obtain the mean velocity  $\langle v_i \rangle$  and the peculiar velocity  $v_i$  which will be used later.

To find the mean velocity  $\langle v_i \rangle$  let  $\phi = v_i$  in equation 3.3, then,

$$\langle v_i \rangle = \frac{1}{N(x_i, t)} \int v_i f(v_i, x_i, t) dc \quad (3.4)$$

We note that whereas  $v_i$ ,  $x_i$  and  $t$  are independent variables and are thus independent of each other,  $\langle v_i \rangle$  is a function of position  $x_i$  and time  $t$ . The peculiar velocity  $v_i$  is defined as the velocity of a molecule relative to the mean velocity. That is,

$$v_i = v_i - \langle v_i \rangle \quad (3.5)$$

Since  $\langle v_i \rangle$  is a function of  $x_i$  and  $t$  then,  $V_i$  is also a function of  $x_i$  and  $t$ . From equation 3.5, we see that the mean value of the peculiar velocity is zero since

$$\langle V_i \rangle = \langle v_i - \langle v_i \rangle \rangle = \langle v_i \rangle - \langle v_i \rangle = 0$$

### 3.3 The Boltzmann Equation

The macroscopic properties or the mean values of a gas can be determined from a knowledge of the velocity distribution function  $f$ . In order to find the time variation of the macroscopic properties it is necessary to obtain an equation describing the time variation of the velocity distribution function. The equation that describes this time variation is the Boltzmann equation. The Boltzmann equation will be derived in two parts, considering first the form which it takes in the absence of collision, and then deriving the collisional term. The collisional term of the Boltzmann equation takes account of binary collisions. In plasma multiple coulomb collisions must also be taken into account.

#### 3.3.1 The Collisionless Boltzmann Equation

Let  $R_i$  be the force per unit mass on a particle in a gas. In most cases the force will not be a function of velocity. However, in case of a plasma a force that is a function of velocity does exist. This is the force on a charged particle moving in a magnetic field given by  $q \vec{v} \times \vec{B}$ , where  $q$  is the charge on the particle. The force per unit mass

$R_i'$  is written as the sum of two terms:  $R_i'$  which is independent of velocity, and the velocity dependent term  $q \vec{v} \times \vec{B}$ . That is,

$$R_i = R_i' + q/m \vec{v} \times \vec{B} \quad (3.4)$$

And from Newton's second law we have that  $R_i = \dot{v}_i$ .

At time  $t$ , the number of molecules in volume element  $dr^{(t)}$  at  $x_i$  with velocities in the velocity element  $dc^{(t)}$  at  $v_i$  is  $f(v_i, x_i, t) dc^{(t)} dr^{(t)}$ . In the time interval  $dt$ , the location of a molecule will change by an amount  $x_i dt = v_i dt$ , while its velocity will change by an amount  $v_i dt = R_i dt$ . Thus, at the time  $t + dt$ , in the absence of any collisions, the number of molecules in the volume element  $dr^{(t+dt)}$  at  $x_i + v_i dt$  with velocities in the velocity element  $dc^{(t+dt)}$  at  $v_i + R_i dt$  is

$f(v_i + R_i dt, x_i + v_i dt, t + dt) dc^{(t+dt)} dr^{(t+dt)}$ . However, these are exactly the same molecules as considered at time  $t$ , so that we can equate the two expressions and obtain:

$$f(v_i, x_i, t) dc^{(t)} dr^{(t)} = f(v_i + R_i dt, x_i + v_i dt, t + dt) dc^{(t+dt)} dr^{(t+dt)} \quad (3.5)$$

The relationship between  $dr^{(t)} dc^{(t)}$  and  $dr^{(t+dt)} dc^{(t+dt)}$  can be determined in the following way. The changes in the volume element  $dc^{(t)}$  and  $dr^{(t)}$  are given by the Jacobian transformation

$$dr^{(t+dt)} = J(r) dr^{(t)} = \frac{\partial (x_i + v_i dt)}{\partial (x_i)} dr^{(t)} \quad (3.6)$$

and

$$dc(t+dt) = J(v) \frac{\partial(v_i + R_i dt + q/m \vec{v} \times \vec{B} dt)}{\partial(v_i)} dc(t) \quad (3.7)$$

since  $v_i$  and  $x_j$  are independent variables we note that in equation 3.6

$$J(r) = \frac{\partial(x_i + v_i dt)}{\partial x_i} = \det \delta_{ij} = 1$$

where det stands for determinant, so that

$$dr(t+dt) = dr(t) \quad (3.8)$$

Expanding the Jacobian in equation (3.7),

$$\begin{vmatrix} 1 - q/m B_3 dt & q/m B_2 dt & \\ q/m B_3 dt & 1 - q/m B_1 dt & \\ - q/m B_2 dt & q/m B_1 dt & 1 \end{vmatrix} = 1$$

If we neglect terms of order  $(dt)^2$ , thus, equation 3.7 can be written as

$$dc(t+dt) = dc(t) \quad (3.9)$$

Using equations (3.8) and (3.9) we can write equation (3.6) as,

$$f(v_i, x_i, t) = f(v_i + R_i dt, x_i + v_i dt, t+dt) \quad (3.10)$$

Expanding the right hand side of equation (3.10) in a Taylor series about  $dt = 0$  we obtain:

$$f(v_i, x_i, t) = f(v_i, x_i, t) + \left| \frac{\partial f}{\partial v_i} R_i dt + \frac{\partial f}{\partial x_i} v_i dt + \frac{\partial f}{\partial t} dt \right| +$$

terms of order  $(dt)^2$ .

Neglecting terms of order  $(dt)^2$  and higher terms we have

$$\frac{\partial f}{\partial t} + v_i \frac{\partial f}{\partial x_i} + R_i \frac{\partial f}{\partial v_i} = 0 \quad (3.11)$$

This is the collisionless Boltzman equation expressing the time dependence of the velocity distribution function. The first term,  $\frac{\partial f}{\partial t}$ , is the local variation of the distribution function. The term  $v_i \frac{\partial f}{\partial x_i}$  is the variation of the distribution function resulting from molecules streaming in and out of a given volume element. The term  $R_i \frac{\partial f}{\partial v_i}$  is the variation of the distribution function resulting from the external forces acting on the molecules.

The distribution function will always vary as a result of collisions between the molecules of the gas. We can include this variation by writing a collisional term on the right hand side of equation (3.11). Thus,

$$\frac{\partial f}{\partial t} + v_i \frac{\partial f}{\partial x_i} + R_i \frac{\partial f}{\partial v_i} = \left(\frac{\partial f}{\partial t}\right)_{\text{coll}} \quad (3.12)$$

The form of this collision term has to be determined. For a gas of low density, where binary collisions only need to be considered, this collision term can be written as an integral known as the collision integral.

### 3.3.2 The Collision Integral

The term  $(\frac{\partial f}{\partial t})_{\text{coll}}$  which appears on the Boltzmann equation represents the time rate of change of the distribution function,  $f$  due to collisions of the molecules with each other. An explicit expression for this term can be obtained by considering the statistical nature of the binary collisions.

For a given distribution function at a specific time  $t$ , there will be a certain number of molecules with velocities in particular regions of the velocity space. That is, there will be a certain number of molecules per unit volume with velocities  $v_i^A$  in  $dc^A$ . This number is  $f(v_i^A) dc^A$  which we write as  $f^A dc^A$ . If as a result of collision, the velocity of a molecule changes from  $v_i^A$  to  $\bar{v}_i^A$ , then we will say that the molecules have been knocked out from the velocity element  $dc^A$  into the velocity element  $d\bar{c}^A$ . Let  $v_i^B$  and  $\bar{v}_i^B$  be the initial and final velocities of a molecule that collided with the above mentioned molecule respectively. That is, to say this molecule was knocked from the velocity element  $dc^B$  into the velocity element  $d\bar{c}^B$ .

Now in order to calculate  $(\frac{\partial f}{\partial t})_{\text{coll}}$  we need to determine the net gain of molecules with velocities in a certain velocity element due to collisions with molecules of all other velocities, taking as our typical molecules those with velocities  $v_i^A$ .

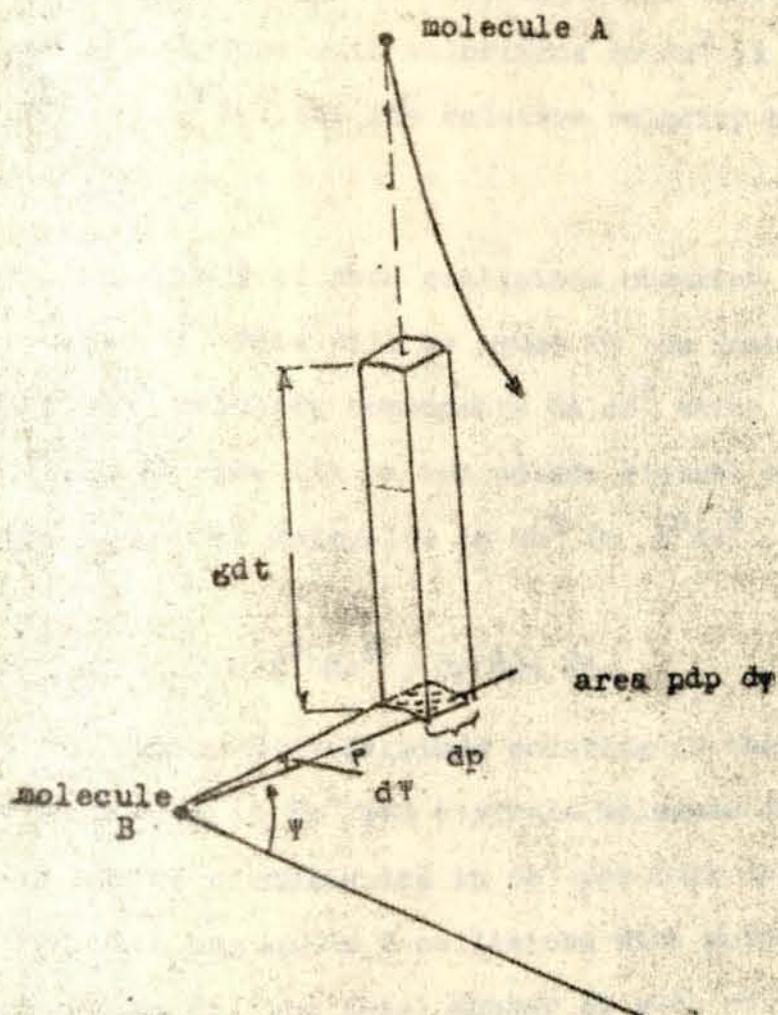


FIG. 4 REPRESENTATION OF COLLISION BETWEEN MOLECULE A AND MOLECULE B

Representation of a collision between molecule A and molecule B.

Consider first the collision in which molecules are knocked out of the velocity element  $dc^A$ . The collision occurs between molecule A with velocity in  $dc^A$  and molecule B with

velocity in  $dc^B$  as shown in Figure 4. The number of molecules per unit volume with velocities in  $dc^B$  is  $f(v_1^B)dc^B$  or  $f^B dc^B$  and the relative velocity between the two molecules is  $g$ .

Let  $T$  be the number of such collisions occurring in the time interval  $dt$ . This will be equal to the number of molecules with velocity components in  $dc^B$  which at a certain instant of time lie in the volume element  $p dp d\psi g dt$ . Since the number of molecules in  $dc^B$  is  $f^B dc^B$ , it follows that,

$$T = f^B dc^B p dp d\psi g dt.$$

This is the number of collisions occurring in the time  $dt$  between molecules in  $dc^B$  and a single molecule in  $dc^A$ . Since the number of molecules in  $dc^A$  per unit volume is  $f^A dc^A$  and each one makes  $T$  collisions with molecules in  $dc^B$  in the time  $dt$ , the total number of such collisions is

$$f^A dc^A T = f^A f^B dc^A dc^B g p dp d\psi dt \quad (3.13)$$

In order to get the total number of molecules that enter into collisions with all molecules of all velocities in the time  $dt$ , we must integrate equation 3.13 with respect to  $dc^B$ ,  $dp$  and  $d\psi$ . Defining this quantity by "out" (molecules knocked out of  $dc^A$ ), we have from equation 3.13

$$\text{"out"} = dc^A dt \int f^A f^B g p dp d\psi dc^B.$$



Using

$$g = \bar{g} \text{ and } dc^A dc^B = d\bar{c}^A d\bar{c}^B \text{ we get:}$$

$$\text{"In" - "out"} = dc^A dt \int (\bar{f}^A \bar{f}^B - f^A f^B) g p dp d\psi dc^B \quad (3.17)$$

Now  $(\frac{\partial f}{\partial t})_{\text{coll}}$  is the rate of change of  $f^A$  due to collision.

The number of molecules per unit volume with velocities in  $dc^A$  at the beginning of  $dt$  is  $f^A dc^A$ . The number of molecules per unit volume with velocity in  $dc^A$  at the end of  $dt$  is  $[f^A + (\frac{\partial f^A}{\partial t})_{\text{coll}} dt] dc^A$ . Thus, the net gain of molecules in  $dc^A$  is,

$$\left(\frac{\partial f^A}{\partial t}\right)_{\text{coll}} = \int (\bar{f}^A \bar{f}^B - f^A f^B) g p dp d\psi dc^B \quad (3.18)$$

In deriving this equation we have considered  $v_1^A$  to be the velocity of our typical molecule. We might as well have chosen any velocity  $v_1$ . In this case  $f(v_1^A) = f^A$  would be  $f(v_1) = f$  and equation (3.18) would be written as

$$\left(\frac{\partial f}{\partial t}\right)_{\text{coll}} = \int (\bar{f} \bar{f}^B - f f^B) g p dp d\psi dc^B \quad (3.19)$$

Using equation (3.19) we can write the Boltzmann equation as

$$\frac{\partial f}{\partial t} + v_1 \frac{\partial f}{\partial x_1} + R_1 \frac{\partial f}{\partial v_1} = \int (\bar{f} \bar{f}^B - f f^B) g p dp d\psi dc^B \quad (3.20)$$

### 3.4 The Equilibrium Solution of the Boltzmann Equation

The equilibrium solution of the Boltzmann equation is used to mean the expression for the velocity distribution function that satisfies the equation when there are no external forces and when interparticle collisions no longer cause any change in the distribution.

Consider a collision between two molecules A and B. If a function  $\phi$  of molecular velocities is associated with each molecule and if the sum of the  $\phi$ 's for the two molecules is conserved during a collision, then  $\phi$  is called a summational invariant. Thus,  $\phi$  has a property that,

$$\phi^A + \phi^B = \bar{\phi}^A + \bar{\phi}^B \quad (3.21)$$

The total energy and the components of linear momentum are conserved during a collision. That is,

$$\frac{1}{2} M v_1 v_1 + \frac{1}{2} M^B v_1^B = \frac{1}{2} M \bar{v}_1 \bar{v}_1 + \frac{1}{2} M^B \bar{v}_1^B \bar{v}_1^B \quad (3.22)$$

and

$$M v_1 + M^B v_1^B = M \bar{v}_1 + M^B \bar{v}_1^B \quad (3.23)$$

Thus,  $M v_1/2$  and  $M v_1$  are summational invariants. A numerical constant is another summational invariant. Equations (3.22) and (3.23) are four equations giving the six quantities  $\bar{v}_1$ ,  $\bar{v}_2$ ,  $\bar{v}_1^B$ ,  $\bar{v}_2^B$  and  $\bar{v}_3^B$  in terms of  $v_1$ ,  $v_2$ ,  $v_3$ ,  $v_1^B$ ,  $v_2^B$  and  $v_3^B$ . Thus, solving these four equations in six unknowns leaves two unknowns to be determined. However, there are two geometrical unknowns required to

specify the collisions completely -  $p$  and  $\psi$  in Fig.4. Knowing these the problem is determined by equations (3.23) and (3.24). Thus, any other summational invariant cannot be independent and must be a linear combination of

$$\phi^{(1)}=1, \quad \phi^{(2)}=Mv_j, \quad \phi^{(3)}=\frac{1}{2} Mv_j^2 \quad v_j \quad (3.24)$$

We wish to determine the form of the distribution function for the case of a uniform gas ( $\frac{\partial f}{\partial x_i} = 0$ ) on which no external forces are acting. The Boltzmann equation becomes:

$$\frac{\partial f}{\partial t} = \int (\bar{f}\bar{f}^B - ff^B) g p dp d\psi dc^B \quad (3.25)$$

For equilibrium or steady state solution - that is a solution for which  $\frac{\partial f}{\partial t} = 0$ , for equation (3.26). This requires that the integral on the right hand side vanish.

Clearly this integral will vanish if,

$$\bar{f}\bar{f}^B - ff^B = 0. \quad (3.26)$$

Equation (3.26) is a necessary and sufficient condition for expression (3.25) to be zero [23]. Taking the natural logarithm of equation (3.26), we obtain,

$$\text{Ln}\bar{f} + \text{Ln}\bar{f}^B = \text{Ln}f + \text{Ln}f^B \quad (3.27)$$

Comparing equations (3.27) and (3.21) we see that  $\text{Ln}f$  must be a summational invariant. Thus, as we have seen, it must be a linear combination of  $\phi^{(1)}$ ,  $\phi_1^{(2)}$  and  $\phi^{(3)}$  given by equation (3.22). That is,

$$\begin{aligned} \text{Ln} f &= \sum_{n=1}^3 \alpha^{(n)} \phi^{(n)} \\ &= \alpha^{(1)} \phi^{(1)} + \alpha_i^{(2)} \phi_i^{(2)} - \alpha^{(3)} \phi^{(3)} \\ &= \alpha^{(1)} + \alpha_i^{(2)} M v_i - \alpha^{(3)} \frac{1}{2} M v_j v_j \end{aligned}$$

where  $\alpha_i^{(2)}$  is a vector having three components. The sign of the constant  $\alpha^{(3)}$  is taken negative for later convenience. Summing over repeated indices gives,

$$\begin{aligned} \text{Ln} f &= \alpha^{(1)} + M(\alpha_1^{(2)} v_1 + \alpha_2^{(2)} v_2 + \alpha_3^{(2)} v_3) \\ &\quad - \frac{1}{2} \alpha^{(3)} M (v_1^2 + v_2^2 + v_3^2) \\ &= \text{Ln} \alpha^{(0)} - \alpha^{(3)} \frac{1}{2} M \left[ \left( v_1 - \frac{\alpha_1^{(2)}}{\alpha^{(3)}} \right)^2 \right. \\ &\quad \left. + \left( v_2 - \frac{\alpha_2^{(2)}}{\alpha^{(3)}} \right)^2 + \left( v_3 - \frac{\alpha_3^{(2)}}{\alpha^{(3)}} \right)^2 \right] \end{aligned}$$

If we write  $\frac{\alpha_i^{(2)}}{\alpha^{(3)}} = \beta_i$ , we obtain,

$$\text{Ln} f = \text{Ln} \alpha^{(0)} - \alpha^{(3)} \frac{1}{2} M \left[ (v_1 - \beta_1)^2 + (v_2 - \beta_2)^2 + (v_3 - \beta_3)^2 \right]$$

or

$$f = \alpha^{(0)} e^{-\alpha^{(3)} \frac{1}{2} M \left[ (v_1 - \beta_1)^2 + (v_2 - \beta_2)^2 + (v_3 - \beta_3)^2 \right]} \quad (3.28)$$

The form of  $f$  given by equation (3.28) is known as the Maxwellian distribution. There are five arbitrary constants,  $\alpha^{(0)}$ ,  $\alpha^{(3)}$ ,  $\beta_1$ ,  $\beta_2$  and  $\beta_3$  which must be determined.

### 3.5 The Maxwellian Distribution

The Maxwellian distribution of particles given by equation (3.28) is the most important velocity distribution in plasma kinetic theory. It is the distribution of a set of particles in collisional equilibrium with themselves. Under these conditions a temperature may be properly assigned to the gas and the various thermodynamic properties of the gas may be discussed. When this condition is not fulfilled, that is to say, when the external forces are too strong to be masked by collisions, the thermodynamic properties cannot be properly applied to the gas. In such a case it may be a very difficult problem to solve the Boltzmann equation for the distribution function. It is therefore important, in plasma problems to know when the particles possess a Maxwellian velocity distribution or when such a distribution may be a good approximation.

In order to determine the five arbitrary constants in equation (3.28), let us make the following change of variables,

$$U_1 = v_1 - \beta_1$$

$$U_2 = v_2 - \beta_2$$

$$U_3 = v_3 - \beta_3$$

Then equation (3.28) becomes

$$f = \alpha^{(0)} e^{-\alpha^{(3)} |U_1^2 + U_2^2 + U_3^2|} \quad (3.29)$$

The mean value of any function was given as ,

$$N \langle \phi \rangle = \int \phi f \, dv_1 \, dv_2 \, dv_3 \quad (3.30)$$

so that,

$$N \langle \phi \rangle = \int \phi \alpha^{(0)} e^{-\alpha(3) \frac{1}{2} M (U_1^2 + U_2^2 + U_3^2)} \, dU_1 \, dU_2 \, dU_3$$

Let  $\phi = U_1$  in equation (3.30), then

$$N \langle U_1 \rangle = \alpha^{(0)} \int_{-\infty}^{\infty} U_1 e^{-\alpha(3) \frac{1}{2} M U_1^2} \, dU_1 \times \int_{-\infty}^{\infty} e^{-\alpha(3) \frac{1}{2} M U_2^2} \, dU_2 \int_{-\infty}^{\infty} e^{-\alpha(3) \frac{1}{2} M U_3^2} \, dU_3 = 0 \quad (3.31)$$

Since the first integral is the integral from  $-\infty$  to  $\infty$  of an odd function  $U_1$ ,  $\langle U_1 \rangle = \langle v_1 - \beta_1 \rangle = \langle v_1 \rangle - \beta_1 = 0$  and therefore,  $\beta_1 = \langle v_1 \rangle$  is the  $x_1$ -component of the mean velocity of the gas. In a similar manner we can show that  $\beta_2 = \langle v_2 \rangle$  and  $\beta_3 = \langle v_3 \rangle$ , so that we can write,

$$U_1 = v_1 - \langle v_1 \rangle = V_1$$

$$U_2 = v_2 - \langle v_2 \rangle = V_2$$

$$U_3 = v_3 - \langle v_3 \rangle = V_3$$

where  $V_1$ ,  $V_2$  and  $V_3$  are the components of the peculiar velocity  $V_i$ . The maxwellian distribution can thus be written as

$$f = \alpha^{(0)} e^{-\alpha(3) \frac{1}{2} M [V_1^2 + V_2^2 + V_3^2]} \quad (3.32)$$

by using  $N \langle \phi \rangle = \int \phi f dv$  and transforming to spherical coordinates, where  $v_1 v_1 = w^2$  and then by letting  $\phi = 1$  and  $\phi = Mv_1 v_1 / 2$  respectively, we can determine  $\alpha^{(0)}$  and  $\alpha^{(3)}$ . The result is that equation (3.32) can be written as,

$$f = N \left( \frac{M}{2\pi kt} \right)^{3/2} e^{-M(w^2/2kt)} \quad (3.33)$$

Thus, we see that for a given number density  $n$ , mean velocity  $\langle v_1 \rangle$ , and temperature  $T$ , there is only one possible equilibrium distribution of molecular velocities and that any different distribution will tend to approach this distribution in the absence of external forces.

CHAPTER 4

GENERATION OF ENTRAINING CURRENTS BY A SLOWLY VARYING

AMPLITUDE WAVE

4.1 Successive Approximation of the Distribution Function.

The evaluation of the current density, energy density and energy flux density is carried out by means of the kinetic theory. The kinetic theory treatment of plasma is based on the Boltzmann equation and Maxwell's equations. Since the solution of the Boltzmann equation is difficult, some approximation procedures are necessary. For rarefied plasma when collision between particles are negligible the collisional term in the Boltzmann equation can be set equal to zero and we get the Vlasov equation. The velocity distribution function can be determined by successive approximation to any desired degree of accuracy. The successive approximations are given by:

$$f^{(0)} + f^{(1)}, f^{(0)} + f^{(1)} + f^{(2)}, \dots$$

and

$$f^{(0)}, f^{(1)}, f^{(2)}, \dots, f^{(r)}$$

are respectively proportional to  $n^1, n^0, n^{-1}$  etc., where  $n$  is the number density of the particles [22]. Hence, the later terms in the approximation become relatively more important as the density decreases. When the density of the gas is comparable with that of the atmosphere near the ground, the terms  $f^{(r)}$  in  $f$  decrease rapidly as  $r$  increases

and  $f^{(0)} + f^{(1)}$  is sufficient good approximation to  $f$  for most purposes. In raref gases, naturally, the later terms are relatively more important, so that some purposes it is worthwhile to determine  $f^{(2)}$  [22].

Consider a homogeneous, isotropic and electrically neutral plasma. There is no constant field which can lead to anisotropic electromagnetic properties and also there is no orderly motion of charged particles which can generate current and bring about non-homogeneous distribution of particles. Under this conditions, the distribution function does not depend upon the coordinates but depends only upon the absolute value of the impulse of the external wave. For this case, the distribution function can be expanded in power series and our treatment will be limited upto the second order approximation. Thus, we can write the distribution function as:

$$f_{\alpha}(\vec{p}, \vec{r}, t) = f_{0\alpha}(\vec{p}) + f_{1\alpha}(\vec{p}, \vec{r}, t) + f_{2\alpha}(\vec{p}, \vec{r}, t) \quad (4.1)$$

where  $f_{0\alpha}(\vec{p})$  is the distribution of  $\alpha$ -sort of particles in the unperturbed state of plasma and  $f_{1\alpha}(\vec{p}, \vec{r}, t)$  and  $f_{2\alpha}(\vec{p}, \vec{r}, t)$  are small additional terms to the distribution function.

The Vlasov equation for rarefied plasma is given by

$$\frac{\partial f}{\partial t} + \vec{v} \cdot \frac{\partial f}{\partial \vec{r}} + e\vec{E} \cdot \frac{\partial f}{\partial \vec{p}} = 0 \quad (4.2)$$

And for the additional terms  $f_1$  &  $f_2$

$$\frac{\partial f_1}{\partial t} + \vec{v} \cdot \frac{\partial f_1}{\partial \vec{r}} + e \vec{E} \cdot \frac{\partial f_1}{\partial \vec{p}} = 0 \quad (4.3)$$

$$\frac{\partial f_2}{\partial t} + \vec{v} \cdot \frac{\partial f_2}{\partial \vec{r}} + e \vec{E} \cdot \frac{\partial f_2}{\partial \vec{p}} = 0 \quad (4.4)$$

When equations (4.3) and (4.4) are integrated in a moment of time  $t_0$ , we get

$$f_1(\vec{p}, \vec{r}, t) = f_1(\vec{p}, \vec{r} - \vec{v}(t-t_0), t_0) - e \frac{\partial f_0}{\partial \vec{p}} \int_{t_0}^t dt' \times \vec{E}(\vec{r} - \vec{v}(t-t'), t') \quad (4.5)$$

and

$$f_2(\vec{p}, \vec{r}, t) = f_2(\vec{p}, \vec{r} - \vec{v}(t-t_0), t_0) - \int_{t_0}^t dt' \times \vec{E}(\vec{r} - \vec{v}(t-t'), t') \cdot \frac{\partial f_1}{\partial \vec{p}}(\vec{p}, \vec{r} - \vec{v}(t-t'), t') \quad (4.6)$$

Now let us consider the electric field of the wave whose amplitude varies slowly with time as

$$\vec{E}(\vec{r}, t) = \vec{E}_0 (1 - e^{-\alpha t}) \cos(\omega t - \vec{k} \cdot \vec{r}) \quad (4.7)$$

where

- $\vec{E}_0$  is the amplitude of the wave
- $\omega$  is the frequency of the wave
- $\vec{k}$  is the wave vector and
- $\alpha$  is the value characterizing the rate of amplitude growth of the wave in the plasma.

At a time,  $t = 0$  the electric field given by equation (4.7) is equal to zero. And

$$f_1(\vec{p}, \vec{r}, t) = f_2(\vec{p}, \vec{r}, t) = 0$$

and when  $t \gg 1/\alpha$

$$\vec{E}(\vec{r}, t) = \vec{E}_0 \cos(\omega t - \vec{k} \cdot \vec{r}).$$

If equation (4.7) is substituted into equations (4.5) and (4.6), we obtain:

$$f_1(\vec{p}, \vec{r}, t) = -e \frac{\partial f_0}{\partial \vec{p}} \int_0^t dt' \vec{E}_0 (1 - e^{-\alpha t'}) \cos|\omega t' - \vec{k} \cdot \vec{r} + \vec{k} \cdot \vec{v}(t-t')| \quad (4.8)$$

and

$$f_2(\vec{p}, \vec{r}, t) = -e \int_0^t dt' \vec{E}_0 (1 - e^{-\alpha t'}) \cos|\omega t' - \vec{k} \cdot \vec{r} + \vec{k} \cdot \vec{v}(t-t')| \cdot \frac{\partial f_1}{\partial \vec{p}} \quad (4.9)$$

If the cosine term in equation (4.8) is written in complex form that is, in the form of

$$\cos \alpha = \frac{e^{i\alpha} + e^{-i\alpha}}{2}$$

we get

$$f_1(\vec{p}, \vec{r}, t) = -\frac{e}{2m} E_{0j} \frac{\partial f_0}{\partial v_j} \int_0^t dt' (1 - e^{-\alpha t'}) \times$$

$$|e^{i|\omega t' - \vec{k} \cdot \vec{r} + \vec{k} \cdot \vec{v}(t-t')|} + e^{-i|\omega t' - \vec{k} \cdot \vec{r} + \vec{k} \cdot \vec{v}(t-t')|} |$$

After integration we obtain

$$\begin{aligned}
 f_1(\vec{p}, \vec{r}, t) &= -\frac{e}{2m} E_{0j} \frac{\partial f_0}{\partial v_j} \left| \frac{e^{i[\omega t' - \vec{k} \cdot \vec{r} + \vec{k} \cdot \vec{v}(t-t')]} }{i(\omega - \vec{k} \cdot \vec{v})} \right|_0^t \\
 &+ \frac{e^{-i[\omega t' - \vec{k} \cdot \vec{r} + \vec{k} \cdot \vec{v}(t-t')]} }{-i(\omega - \vec{k} \cdot \vec{v})} \Big|_0^t - \frac{e^{-\alpha t' + i\omega t' - i\vec{k} \cdot \vec{r} + i\vec{k} \cdot \vec{v}(t-t')}}{-\alpha + i\omega - i\vec{k} \cdot \vec{v}} \Big|_0^t \\
 &+ \frac{e^{-\alpha t' - i\omega t' - i\vec{k} \cdot \vec{v}(t-t') + i\vec{k} \cdot \vec{r}}}{-\alpha - i\omega + i\vec{k} \cdot \vec{v}} \Big|_0^t \\
 &= -\frac{e}{2m} E_{0j} \frac{\partial f_0}{\partial v_j} \left| \frac{e^{i\omega t - i\vec{k} \cdot \vec{r}} - e^{-i\vec{k} \cdot \vec{r} + i\vec{k} \cdot \vec{v}t}}{i\Omega} \right. \\
 &- \frac{e^{-i\omega t + i\vec{k} \cdot \vec{r}}}{i\Omega} + \frac{e^{i\vec{k} \cdot \vec{r} - i\vec{k} \cdot \vec{v}t}}{-\alpha + i\omega - i\vec{k} \cdot \vec{v}} + \frac{e^{-i\vec{k} \cdot \vec{r} + i\vec{k} \cdot \vec{v}t}}{-\alpha + i\omega - i\vec{k} \cdot \vec{v}} \\
 &- \frac{e^{-\alpha t + i\omega t - i\vec{k} \cdot \vec{r}}}{-\alpha + i\Omega} + \frac{e^{-i\vec{k} \cdot \vec{r} - i\vec{k} \cdot \vec{v}t}}{-\alpha + i\Omega} + \frac{e^{-\alpha t - i\omega t + i\vec{k} \cdot \vec{r}}}{\alpha + i\Omega}
 \end{aligned}$$

where  $\Omega = \omega - \vec{k} \cdot \vec{v}$

After some rearrangement we arrive at the following expression for  $f_1(\vec{p}, \vec{r}, t)$ .

$$\begin{aligned}
 f_1(\vec{v}, \vec{r}, t) &= -\frac{e}{2m} E_{0j} \frac{\partial f_0}{\partial v_j} \left\{ \left| e^{-\alpha t} \frac{(\alpha + i\Omega)}{\alpha^2 + \Omega^2} \frac{-i}{\Omega} \right| \times \right. \\
 &e^{i\omega t - i\vec{k} \cdot \vec{r}} + e^{-\alpha t} \frac{(\alpha - i\Omega)}{\alpha^2 + \Omega^2} + \frac{i}{\Omega} e^{-i\omega t + i\vec{k} \cdot \vec{r}}
 \end{aligned}$$

$$+ \frac{i\alpha}{\Omega(\alpha-i\Omega)} e^{i\vec{k}\cdot\vec{v}t - i\vec{k}\cdot\vec{r}} - \frac{i\alpha}{\Omega(\alpha+i\Omega)} e^{-i\vec{k}\cdot\vec{v}t + i\vec{k}\cdot\vec{r}} \quad (4.10)$$

The integration of equation (4.9) in a similar manner and using equation (4.10) yields

$$f_2(\vec{v}, \vec{r}, t) = \frac{1}{i} \left(\frac{e}{2m}\right)^2 E_{0i} E_{0j} \frac{\partial}{\partial v_i} \left(D \frac{\partial f_0}{\partial v_j}\right) \quad (4.11)$$

which is the additional term to the distribution function, and D is given by

$$D = \frac{1}{\Omega - i\alpha} \left[ -\frac{e^{-\alpha t} + 1}{\alpha} + \frac{e^{-2\alpha t} - 1}{2\alpha} - \frac{e^{+i\Omega t} - 1}{i\Omega} - \frac{e^{-\alpha t + i\Omega t} - 1}{\alpha - i\Omega} \right]$$

$$- \frac{1}{\Omega + i\alpha} \left[ -\frac{e^{-\alpha t} + 1}{\alpha} + \frac{e^{-2\alpha t} - 1}{2\alpha} + \frac{e^{-i\Omega t} + 1}{i\Omega} - \frac{e^{-\alpha t - i\Omega t} - 1}{\alpha + i\Omega} \right]$$

$$+ \frac{1}{\Omega} \left[ \frac{1}{i\Omega} (e^{-i\Omega t} + e^{i\Omega t} - 2) - \frac{1}{\alpha + i\Omega} (e^{-\alpha t - i\Omega t} - 1) + \frac{1}{\alpha - i\Omega} (e^{-\alpha t + i\Omega t} - 1) \right]$$

The expression for D can be simplified to yield

$$D = \frac{1}{\Omega^2 + \alpha^2} \left\{ (1 - e^{-\alpha t})^2 + 2(-1 + \cos \Omega t - \frac{\alpha}{\Omega} \sin \Omega t) \right.$$

$$\left. - \frac{2(\Omega^2 + \alpha^2)}{\Omega^2} (\cos \Omega t - 1) + \frac{2\alpha}{\Omega} e^{-\alpha t} \sin \Omega t \right\} \quad (4.12)$$

D has the sense of coefficient of diffusion in velocity space [7].

The expression for D in equation 4.12 can be simplified in two limited cases:

a) when  $\alpha < |\Omega|$  or  $|\omega/k - v_{||}| > \alpha/k$

$$D = \frac{1}{\Omega^2} |(1 - e^{-\alpha t})^2| = \frac{1}{\Omega^2} \quad (4.13)$$

For this case the resonant particles can be neglected.

b) if  $\Omega^2 < \alpha^2$  or  $|\omega/k - v_{||}| < \alpha/k$

$$D = \frac{1}{\alpha^2} |(1 - e^{-\alpha t})^2 - 2\frac{\alpha^2}{\Omega^2}(\cos \Omega t - 1)| \quad (4.14)$$

In the interval  $|\omega/k - v_{||}| < \omega/k$ , the resonant particles must be taken into account.

#### 4.2 Evaluation of the current density, energy density and energy flux density.

In this section, the average velocity, current density, the energy density and the energy flux density are calculated by the second order approximation without taking into account the resonant particles.

$$\begin{aligned} \langle \vec{v}(\vec{r}, t) \rangle &= \frac{1}{N} \int_{-\infty}^{\infty} \vec{v} f_2 d\vec{v} \quad (4.15) \\ &= \frac{1}{iN} \left(\frac{e}{2m}\right)^2 E_{0i} E_{0j} \int_{-\infty}^{\infty} \vec{v} \frac{\partial}{\partial v_i} \left( D \frac{\partial f_0}{\partial v_j} \right) d\vec{v} \end{aligned}$$

After substituting for D from equation (4.13)

$$\begin{aligned} \langle \vec{v}(\vec{r}, t) \rangle &= \frac{1}{N} \left( \frac{e}{2m} \right)^2 E_{oi} E_{oj} \int_{-\infty}^{\infty} \vec{v} \frac{\partial}{\partial v_j} \left( \frac{1}{\Omega^2} \frac{\partial f_0}{\partial v_j} \right) d\vec{v} \\ &= - \frac{1}{N} \left( \frac{e}{2m} \right)^2 E_{oi} E_{oj} \int_{-\infty}^{\infty} \left( \frac{1}{\Omega^2} \frac{\partial f_0}{\partial v_j} \right) d\vec{v} \end{aligned}$$

using the definition for the change of longitudinal dielectric permittivity due to the electrons that is,

$$\delta \epsilon_e = \frac{4\pi e^2}{mk^2} \int_{-\infty}^{\infty} (\vec{k} \cdot \frac{1}{\Omega} \frac{\partial f_0}{\partial \vec{v}}) d\vec{v} \quad |25|$$

the expression for the average velocity can be written in the following form:

$$\langle \vec{v}(\vec{r}, t) \rangle = \frac{\vec{E}_0(\vec{k}, \vec{E}_0)}{16\pi mn} \frac{\partial \delta \epsilon_e}{\partial \omega} \quad (4.16)$$

From equation (4.16), it can be seen that the average velocity is different from zero for longitudinal waves and for this case it can be written as:

$$\langle \vec{v}_n(\vec{r}, t) \rangle = \frac{k_n |\vec{E}_0|^2}{16\pi mn} \frac{\partial \delta \epsilon_e}{\partial \omega} \quad (4.17)$$

The average current density is given by:

$$\langle \vec{j}(\vec{r}, t) \rangle = eN \langle \vec{v}_n(\vec{r}, t) \rangle$$

and after using eq. (4.17) we obtain,

$$\langle \vec{j}(\vec{r}, t) \rangle = \frac{ek_n |\vec{E}_0|^2}{16\pi m} \frac{\partial \delta \epsilon_e}{\partial \omega} \quad (4.18)$$

This expression is similar with the results obtained in the framework of quasi-linear theory [8]. Also it is necessary to note that equation (4.17) was obtained in the limit as  $t \rightarrow \infty$  but, for a finite time interval it is necessary to take into account the factor  $(1 - e^{-\alpha t})^2$  in the expression for coefficient of diffusion which was used for evaluating the average velocity.

The energy density  $w(\vec{r}, t)$  is evaluated as follows:

$$\begin{aligned}
 \langle w(\vec{r}, t) \rangle &= \frac{m}{2n} \int_{-\infty}^{\infty} v^2 f_2 d\vec{v} & (4.19) \\
 &= \frac{m}{2n} \frac{1}{i} \left(\frac{e}{2m}\right)^2 E_{0i} E_{0j} \int_{-\infty}^{\infty} v^2 \frac{\partial}{\partial v_1} \left( D \frac{\partial f_0}{\partial v_j} \right) d\vec{v} \\
 &= \frac{1}{N} \left(\frac{e}{2m}\right)^2 E_{0i} E_{0j} \int_{-\infty}^{\infty} \left(\frac{m}{2}\right) \vec{v} \cdot \left( v_1 \frac{\partial}{\partial v_1} \right) \left( \frac{1}{\Omega^2} \frac{\partial f_0}{\partial v_j} \right) d\vec{v}
 \end{aligned}$$

integrating this equation by parts and using equation (4.16) we obtain,

$$\langle w(\vec{r}, t) \rangle = \frac{(\vec{E}_0 \cdot \vec{k})}{16\pi n k^2} \omega \frac{\partial \delta \epsilon_e}{\partial \omega} - \frac{(\vec{E}_0 \cdot \vec{k})^2}{16\pi n k^2} \delta \epsilon_e \quad (4.20)$$

Taking into account the longitudinal polarization of the wave equation (4.20) can be written as,

$$\langle w_{||}(\vec{r}, t) \rangle = \frac{|\vec{E}_0|^2}{16\pi n} \omega \frac{\partial \delta \epsilon_e}{\partial \omega} - \frac{|\vec{E}_0|^2}{16\pi n} \delta \epsilon_e \quad (4.21)$$

This expression is similar with the value obtained for the energy density obtained by Ginzburg [16].

For the energy flux density  $\vec{g}(\vec{r}, t)$  we have,

$$\langle \vec{g}(\vec{r}, t) \rangle = \frac{1}{N} \frac{m}{2} \int_{-\infty}^{\infty} v^2 \vec{v} f_2 d\vec{v} \quad (4.22)$$

$$= \frac{1}{N} \frac{m}{21} \left(\frac{e}{2m}\right)^2 E_{0i} E_{0j} \int_{-\infty}^{\infty} v^2 \vec{v} \frac{\partial}{\partial v_i} \left( \frac{1}{\Omega^2} \frac{\partial f_0}{\partial v_j} \right) d\vec{v}$$

integrating this equation by parts and using eq. (4.16)

one gets the following expression for the average energy density

$$\begin{aligned} \langle \vec{g}(\vec{r}, t) \rangle = & \left| \frac{\vec{E}_0 (\vec{k} \cdot \vec{E}_0) \omega^2}{32 \pi k^2 N} + \frac{\vec{K} (\vec{K} \cdot \vec{E}_0)^2 \omega^2}{16 \pi k^4 N} \right| \frac{\partial \delta \epsilon_e}{\partial \omega} \\ & - \left| \frac{\vec{E}_0 (\vec{K} \cdot \vec{E}_0) \omega}{16 \pi k^2 N} + \frac{\vec{K} (\vec{K} \cdot \vec{E}_0) \omega}{8 \pi k^4 N} \right| \delta \epsilon_e \end{aligned} \quad (4.24)$$

For longitudinal waves the expression for the energy flux density can be written as,

$$\langle \vec{g}_n(\vec{r}, t) \rangle = \frac{3 |\vec{E}_0|^2 K_n \omega^2}{32 \pi k^2 N} \frac{\partial}{\partial \omega} \delta \epsilon_e - \frac{3 K_n |\vec{E}_0|^2}{16 \pi k^2 N} \delta \epsilon_e \quad (4.25)$$

#### 4.3 Evaluation of the Time During which Resonant Particles can be Neglected

The average velocity of the resonant particles can be calculated using the value of the coefficient of diffusion given by equation (4.14).

$$\langle V_R(\vec{r}, t) \rangle = \frac{1}{N} \int_{-\infty}^{\infty} \vec{v}_R f_2 d\vec{v} \quad (4.26)$$

$$\langle \vec{V}_R(\vec{r}, t) \rangle = \frac{2}{k} \left( \frac{e}{2m} \right)^2 E_{0i} E_{0l} k_j \frac{1}{v_{Te}^3} \left( \frac{1}{2\pi} \right)^{\frac{1}{2}} \frac{1}{k^2} \times$$

$$\int_{-\alpha/k}^{\alpha/k} kv_n \frac{\cos \theta t - 1}{\theta^2} e^{-mv_n^2/2T} d\theta$$

and using

$$v_n = v_p^2, \quad \frac{-m}{T} = -\frac{1}{v_{Te}^2}, \quad kv_n = \omega$$

$$\cos \theta t - 1 = \cos 2a\theta - 1 = -2 \sin^2 a\theta$$

$$\langle \vec{V}_R(\vec{r}, t) \rangle = -\frac{8}{k} \left( \frac{e}{2m} \right)^2 E_{0i} E_{0l} k_j \frac{1}{v_{Te}^3} \left( \frac{1}{2\pi} \right)^{\frac{1}{2}} k_j \frac{\omega}{k^2} \times$$

$$\int_0^{\alpha/k} \frac{\sin^2 a\theta}{\theta^2} e^{-v_p^2/2v_{Te}^2} d\theta \quad (4.27)$$

Denoting the integral  $\int_0^{\alpha/k} \frac{\sin^2 a\theta}{\theta^2} d\theta$  by I then, we can

integrate I by parametric methods as follows:

$$I = \lim_{\substack{b \rightarrow a \\ \beta \rightarrow 0}} \int_0^{\alpha/k} e^{-\beta\theta} \frac{\sin a\theta}{\theta} \frac{\sin b\theta}{\theta} d\theta$$

by differentiating with respect to a the above expression we get,

$$\frac{dI}{da} = \lim_{\substack{b \rightarrow a \\ \beta \rightarrow 0}} \int_0^{\alpha/k} e^{-\beta\theta} \left( \frac{\cos a\theta}{\theta} \frac{\sin b\theta}{\theta} \right) \theta d\theta$$

Using the following trigonometric identities

$$\frac{\sin(a+b)\theta - \sin(a-b)\theta}{\theta} = \frac{2 \cos \theta \sin b\theta}{\theta}$$

where  $\vec{V}_R$  is the velocity of the resonant particles.

$$\begin{aligned} \langle \vec{V}_R(\vec{r}, t) \rangle &= - \frac{2}{N} \left( \frac{e}{2m} \right)^2 E_{oi} E_{oj} \times \\ &\int_{-\infty}^{\infty} \vec{V}_R \frac{\partial}{\partial v_i} \left( \frac{1}{\Omega^2} (\cos \Omega t - 1) \frac{\partial f_o}{\partial v_j} \right) dv \\ &= \frac{2}{N} \left( \frac{e}{2m} \right)^2 E_{oi} E_{oj} \int_{-\infty}^{\infty} \frac{1}{\Omega^2} (\cos \Omega t - 1) \frac{\partial f_o}{\partial v_j} dv \end{aligned}$$

Substituting the Maxwellian distribution for one dimension

$$f_o = N(m/2\pi T) e^{-mv^2/2T}$$

and

$$\frac{\partial f_o}{\partial v_j} = -mv_j/T f_o$$

equation (4.26) can be written as

$$\begin{aligned} \langle \vec{V}_R(\vec{r}, t) \rangle &= -2 \left( \frac{e}{2m} \right)^2 E_{oi} E_{oj} k_j \left( \frac{m}{T} \right) \left( \frac{m}{2\pi T} \right)^{1/2} \frac{1}{k} \times \\ &\int \frac{\alpha/k - kv_{||}}{(\omega - kv_{||})^2} e^{-mv_{||}^2/2T} dv_{||} \\ &- \alpha/k \end{aligned}$$

by making the following change of variables

$$\omega - kv_{||} = \theta \quad dv_{||} = -\frac{d\theta}{k}$$

$$v_p = \omega/k \quad v_{Te} = \sqrt{T/m} \quad a = t/2$$

and by considering the region of applicability of equation

(4.14) we obtain,

Then,

$$\frac{dI}{da} = \lim_{\substack{b \rightarrow a \\ \beta \rightarrow 0}} \frac{1}{2} \left| \int_0^{\alpha/k} e^{-\beta\theta} \frac{\sin(a+b)\theta}{\theta} d\theta - \int_0^{\alpha/k} \frac{\sin(a-b)\theta}{\theta} d\theta e^{-\beta\theta} \right|$$

By letting  $\alpha \rightarrow \infty$  and using

$$\int_0^{\infty} e^{-qx} \frac{\sin px}{x} dx = \frac{\pi}{2} - \tan^{-1} p/q$$

it can be evaluated to yield:

$$\frac{dI}{da} = \lim_{\substack{b \rightarrow a \\ \beta \rightarrow 0}} \frac{1}{2} \left| \frac{\pi}{2} - \tan^{-1} \frac{(a+b)}{\beta} - \frac{\pi}{2} + \tan^{-1} \frac{(a-b)}{\beta} \right|$$

$$= \lim_{\substack{b \rightarrow a \\ \beta \rightarrow 0}} \frac{1}{2} \left| - \tan^{-1} \frac{(a+b)}{\beta} + \tan^{-1} \frac{(a-b)}{\beta} \right|$$

Using  $\int_0^{\infty} \frac{\tan^{-1} x}{a} dx = x \tan^{-1} \frac{x}{a} - \frac{a}{2} \log(a^2 + x^2)$

The above equation can be integrated to yield

$$I = \lim_{\substack{b \rightarrow a \\ \beta \rightarrow 0}} - \left| \frac{a+b}{2} \tan^{-1} \frac{(a+b)}{\beta} - \frac{\beta}{4} \log(\beta^2 + (a+b)^2) \right.$$

$$\left. - \frac{(a-b)}{2} \tan^{-1} \frac{(a-b)}{\beta} + \frac{\beta}{4} \log(\beta^2 + (a-b)^2) \right|$$

$$I = \lim_{\substack{b \rightarrow a \\ \beta \rightarrow 0}} - \left[ \frac{a+b}{2} \tan^{-1} \frac{a+b}{\beta} - \frac{(a-b)}{2} \tan^{-1} \frac{a-b}{\beta} \right. \\ \left. + \frac{\beta}{4} \log \left( \frac{\beta^2 + (a-b)^2}{\beta^2 + (a+b)^2} \right) + C \right]$$

and after the evaluation of the limit we finally get,

$$I = -\frac{\pi}{2} a, \text{ and since } a = t/2, \quad I = -\frac{\pi t}{4}$$

Substituting this value of I into equation (4.27) we get for the average velocity of the resonant particles the following expression,

$$\langle \vec{v}_R(\vec{r}, t) \rangle = \frac{2}{k^2} \left( \frac{e}{2m} \right)^2 \frac{1}{v_{Te}^3} \left( \frac{1}{2\pi} \right)^{1/2} |\vec{E}_0|^2 e^{-v^2/2v_{Te}^2} \cdot \omega \pi t \\ = \frac{1}{2} \sqrt{\frac{\pi}{2}} \frac{e^2 \omega t}{m^2 k^2 v_{Te}^3} |\vec{E}_0|^2 e^{-v^2/2v_{Te}^2} \quad (4.8)$$

From equation (4.28) we see that the average velocity of the resonant particles increases with time, whereas the average velocity of the non-resonant particles as given by equation (4.16) is independent of time.

Now, let us estimate the time during which it is possible to neglect the contribution of the resonant particles in

evaluating the current density produced by using waves with a slowly varying amplitude. From the condition,

$$\langle \vec{V}_{N,R}(\vec{r}, t) \rangle \gg \langle \vec{V}_R(\vec{r}, t) \rangle$$

where  $\vec{V}_{N,R}$  is the velocity of the non resonant particles we get the limitation on time. By using equation (4.16) for the average velocity of the non-resonant particles and equation (4.28) for the resonant particles and after simplification we get,

$$\omega t \ll \frac{k^3 v_{Te}^3}{\omega_L^2} e^{v_p^2/2v_{Te}^2} \sqrt{\frac{2}{\pi}} \frac{\partial}{\partial \omega} \delta \epsilon_e \quad (4.29)$$

where  $\omega_L$  is the Langmuir frequency for longitudinal waves,

$$\delta \epsilon_e = - \omega_L^2 / \omega^2 \quad \text{and} \quad \frac{\partial}{\partial \omega} \delta \epsilon_e = 2 \omega_L^2 / \omega^3$$

Then equation (4.29) can be written as

$$\omega t \ll 2 \sqrt{\frac{2}{\pi}} (v_{Te} / v_p)^3 e^{v_p^2/2v_{Te}^2} \quad (4.30)$$

From equation (4.30) we note that on the right hand side there is an exponential large term and for a considerable time the current produced is determined by the non-resonance particles. Therefore, during the time given by the inequality of expression (4.30) the effect of the resonant particles can be neglected.

CONCLUSION

In this thesis the mechanism of generation of entraining currents with a slowly varying amplitude high frequency electromagnetic wave was considered. It was shown that non-stationary amplitude leads to the generation of entraining currents. And these currents are produced only if the wave is longitudinal. Using the Vlasov equation the quasi-stationary additional term to the distribution function appearing in the second order approximation was determined. With the help of this term, the current density, energy density and energy flux density in the field of the longitudinal wave were evaluated. The formula for the additional term was investigated as when the resonant and non resonant particles can be neglected, That is when,

$$\alpha < | \omega - KV_{11} |$$

the resonant particles can be neglected and when  $\alpha > | \omega - KV_{11} |$  the non-resonant particles can be neglected. It was shown that during the time determined by the inequality

$$\omega t \ll \sqrt{\frac{2}{\pi}} \cdot K^3 \frac{V_{Te}^3}{\omega L_e} \frac{\partial}{\partial \omega} \delta \epsilon_e$$

the group of resonant particles do not play an important role in the production of entraining currents when a slowly varying amplitude high frequency electromagnetic wave is applied to homogeneous plasma.

The results are presented in terms of the longitudinal dielectric permittivity and its derivatives with respect to frequency. The above method of generating entraining currents may be used in a rarefied plasma when collision between particles are seldom. This method could be used in tokamaks to produce continuous toroidal currents, but it needs further investigation.

1. ... "Radio Frequency Currents Induced in Fusion Reactor Plasmas", Journal of Plasma Physics, 4:130-4, 1962.
2. Fish, R.D., "Current Generation with Low Frequency Waves", Journal of Plasma Physics, 24-25, 1961.
3. Taylor, T.J. & Rosenbluth, M.N., "Low Cyclotron Frequency Heating and the Alpha Ray Cyclotron Instability", Journal of Plasma Physics, 20-21, 1960.
4. ... "Currents Induced by Electromagnetic Waves", Journal of Plasma Physics, 7:1-10, 1963.
5. ... "Theory of Currents Induced by Electromagnetic Waves in a Plasma", Journal of Plasma Physics, 14-15, 1960.
6. ... "Currents Induced by Electromagnetic Waves in a Plasma", Journal of Plasma Physics, 14-15, 1960.
7. ... "Currents Induced by Electromagnetic Waves in a Plasma", Journal of Plasma Physics, 14-15, 1960.
8. ... "Currents Induced by Electromagnetic Waves in a Plasma", Journal of Plasma Physics, 14-15, 1960.
9. ... "Currents Induced by Electromagnetic Waves in a Plasma", Journal of Plasma Physics, 14-15, 1960.
10. ... "Currents Induced by Electromagnetic Waves in a Plasma", Journal of Plasma Physics, 14-15, 1960.

REFERENCES

1. Thompson, W.B., "Introduction to Plasma Physics", Vienna, IAEA, 1965.
2. Okawa, T., "New Methods of Driving Plasma Current in Fusion Devices", Physical Review Letters, 10:185, 1970.
3. Manheimer, W.M.; Winsor, N.K., "Injection of Intense Pulsed Ion Beams into Tokamaks with Application to Plasma Heating and Current Maintenance". Nuclear Fusion 21:1559, 1981.
4. Bharda, D.K. and Chu, C., "Radio Frequency Current Drive in Fusion Producing Plasma", Physical Review Letters 48:1824, 1982.
5. Fish, N.J., "Current Generation with Low Frequency Waves", Physics of Fluids, 24:27, 1981.
6. Tajima, T.; Dawson, J.M., "Ion Cyclotron Resonance Heating and the Alfvén Ion Cyclotron Instability", Nuclear Fusion, 20:1129, 1980.
7. Karney, C.F.F.; Fisch, N.J., "Currents Driven by Electron Cyclotron Waves", Nuclear Fusion, 21:1549, 1981.
8. Kanemitsu Kato., "Theory of Current Generation by Electrostatic Traveling Waves in Collisionless Magnetized Plasma", Physical Review Letters, 44:774, 1980.
9. Grycz, B. Fourth State of Matter. London: Iliffe Books Ltd., 1966.
10. Bishop, A.S., Project Sherwood: Massachusetts: Addison - Wesley, 1958.

11. Bopin, H.A.B., Nuclear Fusion Research. Tripoli: Arab Development Institute, 1980.
12. Rutherford, P., "The Tokamak: 1955-80", Nuclear Fusion 20:1086, 1980.
13. Spitzer, L., Physics of Fully Ionized Gases. New York: Interscience Publishers, 1962.
14. Thonemann, P.C., et al, "Interaction of Travelling Waves with Ionized Gases", Nature, 169:34, 1952.
15. Landau L.L., Lifshits, E.M., Theory of Fields, Moscow, Nauka, 1978.
16. Ginzburg, V.L., Theoretical Physics and Astrophysics. London: Pergamon Press, 1979.
17. Ginzburg, V.L., The Propagation of Electromagnetic Waves in Plasma. Reading Massachusetts: Addison Wesley Company, 1964.
18. Fresh, N.S., "Confining a Tokamak Plasma with rf - driven Currents, Physical Review Letters, 41:873, 1978.
19. Jobs, F. et al, "Formation of a 100-KA Tokamak Discharge in the Princeton Large Torus by Lower Hybrid Waves" Physical Review Letters 52:1005, 1984.
20. Wong, K.L., "Experimental Observation of Current Generation by Unidirectional Electron Plasma Waves" Physical Review Letters, 43:438, 1979.

21. Fisch, N.J., Boozer, A.H., "Creating an Assymetric Plasma Resistivity with Waves". Physical Review Letters. 45:720, 1980.
22. Chapman, S. and Cowling, T.G., The Mathematical Theory of non Uniform Gases. Cambridge: Cambridge University Press, 1952.
23. Holt, E.H., and Haskel, R.E., Foundations of Plasma Physics. New York: Macmillan Comp., 1965.
24. Rudakov, L.I., Plasma Physics and the Problem of Controlled Thermonuclear Reaction. London: Pergamon Press, 1960.
25. Silin, W.P., Ruhadge, A.A., Electromagnetic Properties of Plasma. Mowcow: Atomizdat, 1961.
26. Landau, L.L., Lifshitz, E.M., The Classical Theory of Fields. Oxford: Pergamon Press, 1975.
27. Glasstone, S., Controlled Thermonuclear Rechons an Intro-duction to Theory and Experiment. Princeton; D. VAN Nostround Company, 1960.

DECLARATION

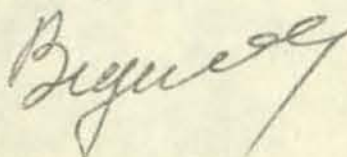
I hereby declare that the thesis entitled, "Entraining Currents in Homogeneous Plasma", being submitted by me in partial fulfillment for Master of Science Degree in Physics, is my original work, done under the supervision and guidance of Dr. V. Schepilov. Sources of relevant findings and equations taken from books and articles are duly acknowledged in the body of the thesis and the reference.

Tesfaye Abraha



The Thesis was submitted to  
the Physics Department  
Graduate Committee on June, 1985

This Thesis has been submitted for examination with my approval as University Advisor.



V. Schepilov, Ph.D.